

Exponentially Fitted Symplectic Runge-Kutta-Nyström methods

Th. Monovasilis¹, Z. Kalogiratou², T.E. Simos³

¹ Department of International Trade, Technological Educational Institution of Western Macedonia at Kastoria, Kastoria, Greece

² Department of Informatics & Computer Technology, Technological Ed. Institution of Western Macedonia at Kastoria, Greece

³ Department of Mathematics, College of Sciences, King Saud University, Riyadh, KSA, Department of Computer Science and Technology, Faculty of Science and Technology, University of Peloponnessos, Greece

Received: 17 Jun 2012; Revised 17 Sep. 2012 ; Accepted 18 Sep. 2012

Published online: 1 Jan. 2013

Abstract: In this work we consider symplectic Runge Kutta Nyström (SRKN) methods with three stages. We construct a fourth order SRKN with constant coefficients and a trigonometrically fitted SRKN method. We apply the new methods on the two-dimensional harmonic oscillator, the Stiefel-Bettis problem and on the computation of the eigenvalues of the Schrödinger equation.

Keywords: Runge Kutta Nyström methods, symplectic methods, exponential fitting

1. Introduction

Hamiltonian systems are systems of first order ordinary differential equations that can be expressed as

$$p' = -\frac{\partial H}{\partial q}(p, q, x), \quad q' = \frac{\partial H}{\partial p}(p, q, x), \quad (1)$$

where $(p, q) \in U$ an open subset of \mathbb{R}^{2d} , $x \in I$ an open subinterval of \mathbb{R} , the integer d is the number of degrees of freedom. The hamiltonian function $H(p, q, x)$ is a twice continuously differentiable function on $U \times I$ that represents the total mechanical energy. The q variables are generalized coordinates and the p variables are the conjugated generalized momenta. The solution operator of a Hamiltonian system is a symplectic transformation.

A symplectic numerical method preserves the symplectic structure in the phase space when applied to Hamiltonian problems. Therefore symplectic numerical methods have been used for the numerical integration of hamiltonian problems over the past two decades. In this work we shall consider problems with separable Hamiltonian of the special form

$$H(p, q, x) = \frac{1}{2}p^T p + V(q, x), \quad (2)$$

then the Hamiltonian system has the form

$$p' = -\frac{\partial}{\partial q}V(q, x), \quad q' = p. \quad (3)$$

or

$$q'' = -\frac{\partial}{\partial q}V(q, x). \quad (4)$$

The last is a system of second order differential equations and have been treated in the literature by Runge-Kutta-Nyström (RKN) and symplectic RKN (SRKN) methods. The theory of these methods can be found in the book of Sanz-Serna and Calvo [4].

On the other hand the solution of hamiltonian systems often has an oscillatory or periodic behavior and special methods that take into account these properties of the solution have been considered. Among these methods are frequency dependent methods as exponentially, trigonometrically fitted, phase fitted and amplification fitted methods and methods with constant coefficients as minimum phase lag, minimum amplification error, P-stable methods. Exponentially fitted methods integrate exactly differential systems whose solutions can be expressed as linear combinations of functions of the form $\exp(\lambda x)$, $\exp(-\lambda x)$ or $\sin(\lambda x)$, $\cos(-\lambda x)$. A detailed survey of these methods can be found in Ixaru and Vanden Berghe. Simos [5] first constructed an exponentially fitted Runge-Kutta method

* Corresponding author: e-mail: tsimos.conf@gmail.com, tsimos@mail.ariadne-t.gr

that integrates exactly the test equation $y'' = -w^2y$. More recently some authors [2] [3] have proposed several exponentially fitted RKN methods. The idea of combining symplecticity with exponential fitting was first introduced by Simos and Aguiar [6] for RKN methods, they presented a two stages modified second order symplectic RKN, also Vyver [7] constructed a two stages modified second order symplectic RKN method that integrates exactly the exponential function at the internal stage also.

Van de Vyver [8] first constructed a symplectic Runge-Kutta-Nyström method with minimum phase-lag. His method has third algebraic order and sixth phase-lag order.

In this work we present two three stages symplectic RKN methods, one with constant coefficients and fourth algebraic order and symplectic modified RKN method which integrates exactly the test equation $y'' = -w^2y$ following the approach of Simos. In section two the basic theory of SRKN methods and exponential fitting is presented, the new methods are developed in section 3. Numerical results and conclusions are presented in section 4.

2. Symplectic RKN methods

We consider systems of second order ODEs of the form

$$y''(x) = f(x, y(x)), \quad x \in [x_0, X],$$

with initial conditions

$$y(x_0) = y_0, \quad y'(x_0) = y'_0.$$

An explicit RKN method is of the form

$$y_{n+1} = y_n + hy'_n + h^2 \sum_{i=1}^s \beta_i f_i,$$

$$y'_{n+1} = y'_n + h \sum_{i=1}^s b_i f_i, \quad (5)$$

where

$$f_i = f \left(x_n + c_i h, y_n + c_i h y'_n + h^2 \sum_{j=1}^{i-1} a_{ij} f_j \right)$$

and is associated with the Butcher tableau

c_1	
c_2	a_{21}
c_3	$a_{31} \quad a_{32}$
\vdots	$\vdots \quad \vdots$
c_s	$a_{s1} \quad a_{s2} \quad \cdots \quad a_{s,s-1}$
	$\beta_1 \quad \beta_2 \quad \cdots \quad \beta_{s-1} \quad \beta_s$
	$b_1 \quad b_2 \quad \cdots \quad b_{s-1} \quad b_s$

Suris showed that a RKN method is symplectic when applied to Hamiltonian problems of the form (2) if the coefficients of the method satisfy

$$\beta_i = b_i(1 - c_i), \quad 1 \leq i \leq s, \quad (6)$$

$$b_i(\beta_j - \alpha_{ij}) = b_j(\beta_i - \alpha_{ji}), \quad 1 \leq i, j \leq s. \quad (7)$$

A RKN method that satisfies (6) and (7) is called symplectic RKN method (SRKN). In the case of explicit RKN methods the coefficients a_{ij} are fully determined by the coefficients b_i and c_i

$$a_{ij} = b_j(c_i - c_j). \quad (8)$$

Condition (6) is a well known simplifying assumption from the standard theory of RKN methods that reduces the number of order conditions. Calvo and Sanz-Serna has shown that condition (7) is also a simplifying assumption. The order conditions up to fourth order method are

first order

$$b.e = 1,$$

second order

$$b.c.e = \frac{1}{2},$$

third order

$$b.c^2.e = \frac{1}{3}, \quad b.a.e = \frac{1}{6},$$

fourth order

$$b.c^3.e = \frac{1}{4}, \quad b.a.c.e = \frac{1}{24}.$$

3. Construction of the new methods

We consider the three stage method

c_1			
c_2	$b_1(c_2 - c_1)$		
c_3	$b_1(c_3 - c_1)$	$b_2(c_3 - c_2)$	
	$b_1(1 - c_1)$	$b_2(1 - c_2)$	$b_3(1 - c_3)$
	b_1	b_2	b_3

In order to construct the fourth order method we solve the six conditions and derive the following coefficients

$$b_1 = \frac{3 - 2\sqrt{3}}{12}, \quad b_2 = \frac{1}{2}, \quad b_3 = \frac{3 + 2\sqrt{3}}{12},$$

$$c_1 = \frac{3 + \sqrt{3}}{6}, \quad c_2 = \frac{3 - \sqrt{3}}{6}, \quad c_3 = c_1.$$

Here we construct new trigonometrically fitted RKN method following the approach introduced by Simos [5] for Runge-Kutta methods. These methods integrate exactly the test equation

$$y'' = -w^2y$$

For the exponentially fitted case we want the numerical method to integrate exactly the exponential function $\exp(\pm wx)$ with w real

$$\exp(\pm v) = 1 \pm v + (\beta.e)v^2 \pm (\beta.C.e)v^3 + (\beta.A.e)v^4 \pm (\beta.A.C.e)v^5 + (\beta.A.A.e)v^6,$$

$$\exp(\pm v) = 1 \pm (b.e)v + (b.C.e)v^2 \pm i(b.A.e)v^3 + (b.A.C.e)v^4 \pm (b.A.A.e)v^5,$$

where $v = wh$. For the trigonometrically fitted case we want the numerical method to integrate the exponential function $\exp(iwx)$ with w real

$$\exp(iv) = 1 + iv - (\beta.e)v^2 - i(\beta.C.e)v^3 + (\beta.A.e)v^4 + i(\beta.A.C.e)v^5 - (\beta.A.A.e)v^6,$$

$$\exp(iv) = 1 + i(b.e)v - (b.C.e)v^2 - i(b.A.e)v^3 + (b.A.C.e)v^4 + i(b.A.A.e)v^5,$$

or equivalently

$$\begin{aligned} \cos v - 1 &= -(\beta.e)v^2 + (\beta.A.e)v^4 - (\beta.A.A.e)v^6, \\ \frac{\sin v}{v} &= 1 - (\beta.C.e)v^2 + (\beta.A.C.e)v^4, \\ \cos v - 1 &= -(b.C.e)v^2 + (b.A.C.e)v^4, \\ \frac{\sin v}{v} &= (b.e) - (b.A.e)v^2 + (b.A.A.e)v^4, \end{aligned} \tag{9}$$

We let $c_1 = 0$ from the trigonometrical fitting conditions (9) we obtain the coefficients

$$c_3 = \frac{c_2v + (-1 + c_2(-1 + b_1v^2))(v \cos v - \sin v)}{v(1 + (-1 + b_1c_2v^2) \cos v - c_2v \sin v)}$$

$$b_3 = -\frac{(1 + (-1 + b_1c_2v^2) \cos v - c_2v \sin v)^2}{p}$$

$$b_2 = \frac{-2 + (2 - b_1v^2) \cos v + (1 + b_1)v \sin v}{p}$$

$$p = v(v + b_1(-1 + c_2)c_2v^3)v \cos v + (-1 + (1 + b_1)c_2v^2 - c_2^2v^2)v \sin v$$

We have two free parameters c_2 and b_1 and we use them in order to obtain the higher possible algebraic order when $v = 0$. This is the case for

$$c_2 = \frac{1}{3} - \frac{1}{6}\sqrt{1+k} - 1/6\sqrt{2-k + \frac{2}{\sqrt{1+k}}},$$

$$k = -\frac{3^{2/3}}{2(-3 + 2\sqrt{3})^{1/3}} + \frac{3^{1/3}(-3 + 2\sqrt{3})^{1/3}}{2}$$

$$b_1 = \frac{-3c_2 + 24c_2^2 - \sqrt{3}\sqrt{-8c_2 + 39c_2^2 - 72c_3^3 + 48c_4^4}}{12(2c_2 + 3c_2^2)}$$

(or $c_2 = -0.18799161879915978201$ and $b_1 = 0.552924973878536667$).

The classical method (for $v = 0$) has algebraic order 3 and the first condition of the fourth order is also satisfied.

For small values of h we use the following Taylor expansions

$$\begin{aligned} b_2 &= -0.18799161879915978201 + 0.014823031830119705447 v^2 \\ &\quad - 0.0006567635698988819674 v^4 + 0.00005008999261903756659 v^6 \\ &\quad - 2.2837596032644413 \cdot 10^{-6} v^8 + 1.6950437269127458 \cdot 10^{-7} v^{10}, \end{aligned}$$

$$b_3 = 0.635066644920623115 - 0.01482303183011970545 v^2$$

$$\begin{aligned} &-0.001438399281608581791 v^4 + 0.0000827946627077300777 v^6 \\ &-1.4655145815655087 \cdot 10^{-6} v^8 + 2.9118114430067654 \cdot 10^{-8} v^{10}, \end{aligned}$$

$$\begin{aligned} c_3 &= 0.73166990421824007504 - 0.01164255863026712775 v^2 \\ &\quad - 0.000354772795572808874 v^4 - 0.0000250077938624870232 v^6 \\ &\quad - 5.568816130391094 \cdot 10^{-7} v^8 - 5.801982609741059 \cdot 10^{-8} v^{10}. \end{aligned}$$

4. Numerical Results

We shall compare our new methods Meth1 (constant coefficients) and Meth2 (variable coefficients) with the third algebraic order with 6th phase lag order SRKN method of Vyver [8] and the fourth order five stages SRKN method of Calvo and Sanz-Serna.

4.1. The two-dimensional harmonic oscillator

We consider the two-dimensional harmonic oscillator

$$p_1' = -w_1 q_1, \quad q_1' = p_1 \quad p_2' = -w_2 q_2, \quad q_2' = p_2$$

with initial conditions

$$p_1(0) = 0, \quad q_1(0) = 1, \quad p_2(0) = 1, \quad q_2(0) = 0.$$

The Hamiltonian of this problem is

$$H(p_1, p_2, q_1, q_2) = T(p_1, p_2) + V(q_1, q_2),$$

$$T(p_1, p_2) = \frac{1}{2}(p_1^2 + p_2^2),$$

and

$$V(q_1, q_2) = -\frac{1}{2}(w_1 q_1^2 + w_2 q_2^2).$$

The exact solution is

$$q_1(x) = \cos w_1 x, \quad q_2(x) = \sin w_2 x,$$

we choose $w_1 = w_2 = 1$. For this choice we use $v = h$. In Table 1 we present the norm of the error in the solution (first line) and the error in the Hamiltonian (second line) for the two-dimensional harmonic oscillator with integration interval $[0, 1000]$ and several stepsizes.

h	Meth1	Meth2	Vyver3	CSS4
1	4.41 10 ⁻¹ 7.11 10 ⁻⁵	4.39 10 ⁻⁶ 6.66 10 ⁻¹⁵	3.14 10 ⁻² 3.01 10 ⁻⁵	7.52 10 ⁻² 3.50 10 ⁻⁷
1/2	2.32 10 ⁻² 2.26 10 ⁻⁷	9.52 10 ⁻¹⁰ 1.65 10 ⁻¹⁵	5.36 10 ⁻⁴ 9.63 10 ⁻⁸	4.61 10 ⁻³ 9.87 10 ⁻¹⁰
1/4	1.42 10 ⁻³ 8.41 10 ⁻¹⁰	2.39 10 ⁻¹³ 4.77 10 ⁻¹⁵	1.60 10 ⁻⁵ 3.59 10 ⁻¹⁰	2.89 10 ⁻⁴ 3.57 10 ⁻¹²

Table 1: The norm of the error in the solution and the error in the Hamiltonian for the two-dimensional harmonic oscillator.

4.2. An orbit problem studied by Stiefel and Bettis

We consider the following almost periodic orbit problem studied by Stiefel and Bettis

$$\begin{aligned} p_1' &= -q_1 + 0.001 \cos(x), & q_1' &= p_1, \\ p_2' &= -q_2 + 0.001 \sin(x), & q_2' &= p_2 \end{aligned}$$

with initial conditions

$$p_1(0) = 0, \quad q_1(0) = 1, \quad p_2(0) = 0.9995, \quad q_2(0) = 0.$$

The analytical solution is given by

$$\begin{aligned} q(x) &= \cos(x) + 0.0005x \sin(x), \\ p(x) &= \sin(x) - 0.0005x \cos(x). \end{aligned}$$

In Table 2 we present the norm of the error in the solution for this problem with integration interval $[0, 1000]$ and several stepsizes.

h	<i>Meth1</i>	<i>Meth2</i>	<i>Vyver3</i>	<i>CSS4</i>
1/2	$2.38 \cdot 10^{-2}$	$3.68 \cdot 10^{-5}$	$4.66 \cdot 10^{-4}$	$4.78 \cdot 10^{-3}$
1/4	$1.42 \cdot 10^{-3}$	$2.22 \cdot 10^{-6}$	$1.33 \cdot 10^{-5}$	$2.98 \cdot 10^{-4}$
1/8	$8.78 \cdot 10^{-5}$	$1.38 \cdot 10^{-7}$	$1.74 \cdot 10^{-6}$	$1.86 \cdot 10^{-5}$
1/16	$5.48 \cdot 10^{-6}$	$8.58 \cdot 10^{-9}$	$2.19 \cdot 10^{-7}$	$1.16 \cdot 10^{-6}$

Table 2: The norm of the error in the solution for the Stiefel-Bettis problem.

4.3. Computation of the eigenvalues of the Schrödinger equation

We shall use our new methods for the computation of the eigenvalues of the one-dimensional time-independent Schrödinger equation. The Schrödinger equation may be written in the form

$$-\frac{1}{2}\psi'' + V(x)\psi = E\psi$$

where E is the energy eigenvalue, $V(x)$ the potential, and $y(x)$ the wave function.

4.3.1. The harmonic oscillator

We consider the harmonic oscillator potential

$$V(x) = \frac{1}{2}kx^2$$

with boundary conditions $\psi(-R) = \psi(R) = 0$. We consider $k = 1$.

The exact eigenvalues are given by

$$E_n = n + \frac{1}{2}, \quad n = 0, 1, 2, \dots$$

	R	<i>Meth1</i>	<i>Meth2</i>	<i>Vyver3</i>	<i>CSS</i>
E_0	5	0	0	0	0
E_{10}	7	7	0	0	2
E_{30}	10	160	3	2	32
E_{50}	12	739	4	12	149
E_{100}	16	6123	9	187	1179
E_{150}	19	–	13	971	3977
E_{200}	22	–	18	3171	–
E_{300}	26	–	35	–	–
E_{400}	30	–	92	–	–

Table 3: Absolute Error ($\times 10^{-6}$) of the eigenvalues of the harmonic oscillator ($h = 0.05$).

4.3.2. The doubly anharmonic oscillator

The potential of the doubly anharmonic oscillator is

$$V(x) = \frac{1}{2}x^2 + \lambda_1 x^4 + \lambda_2 x^6$$

we take $\lambda_1 = \lambda_2 = 1/2$. The integration interval is $[-R, R]$. In Table 4 we give the computed eigenvalues up to E_{20} with step $h = 1/40$ and $R = 3$.

	<i>Meth1</i>	<i>Meth2</i>	<i>Vyver3</i>	<i>CSS</i>
54.222484	117	17	3	20
67.29805	220	25	5	40
81.262879	384	35	9	71
96.061534	630	49	13	120
111.647831	987	64	19	190
127.982510	1486	81	28	288
145.031661	2162	102	38	424
162.765612	3067	123	60	613
181.158105	–	137	85	829
200.185694	–	147	121	1123

Table 4: Absolute Error ($\times 10^{-6}$) of the eigenvalues of the doubly anharmonic oscillator ($h = 1/40$).

We see that the performance of the trigonometrically fitted method is superior in comparison to the other methods tested. Furthermore the computational cost is the same for the three methods with three stages only the 4th order method of Calvo and Sanz-Serma is more expensive.

Acknowledgement

This research has been co-funded by the European Union (European Social Fund) and Greek national resources under the framework of the "Archimedes III: Funding of Research Groups in TEI of W. Macedonia" project of the title "Numerical Integration of Differential Equations with Oscillatory or Periodic Solution", project No. MIS383583.

References

- [1] L. Gr. Ixaru, G. Vanden Berghe, Exponential Fitting, Kluwer Academic Publishers, 2004.
- [2] Z. Kalogiratou, Th. Monovasilis, T.E. Simos, New modified RungeKuttaNyström methods for the numerical integration of the Schrodinger equation, *Computers and Mathematics with Applications* 60, 6 (2010) 16391647.
- [3] Z. Kalogiratou, Th. Monovasilis, T.E. Simos, Computation of the eigenvalues of the Schrodinger equation by exponentially-fitted RungeKuttaNyström methods, *Computer Physics Communications* 180, 2 (2009) 167176.
- [4] J.M. Sanz-Serna, M.P. Calvo, *Numerical Hamiltonian Problem*, Chapman and Hall, London, 1994.
- [5] T.E. Simos, An exponentially-fitted Runge-Kutta method for the numerical integration of initial-value problems with periodic or oscillating solutions, *Computer Physics Communications* 115(1998)1-8.
- [6] T.E. Simos, J.V. Aguiar, Exponentially fitted symplectic integrator, *Physical Review E* 67(2003) 016701.
- [7] H. Van de Vyver, A symplectic exponentially fitted modified Runge-Kutta-Nyström method for the numerical integration of orbital problems, *New Astronomy*, 10(2005)261-269.
- [8] H. Van de Vyver, A symplectic RungeKuttaNyström method with minimal phase-lag, *Physics Letters A* 367 (2007) 1624.



Theodoros Monovasilis (b. 1969 in Kastoria, Greece) is an Associate Professor at the Department of International Trade of the Technological Educational Institute of Western Macedonia at Kastoria Greece since March 2008 as well as collaborator from 1996. Dr Monovasilis received his B.Sc. degree in Mathematics from the University of Ioan-

nina, Greece, in 1992. He studied Applied Mathematics on postgraduate level in Democritus University of Thrace-Greece in 2002. In 2006 he received his Ph.D. degree in Applied Mathematics of the University of Peloponnese (2006). He has participated in various research programs of the Technological Educational Institute of Western Macedonia with object the Applied Mathematics and Numerical Analysis. His research interests focus on Applied Mathematics and more specifically in the numerical solution of differential equations. He is the author of over 40 peer-reviewed publications in these areas and he is referee in scientific journals and conferences.

Zacharoula Kalogiratou (b. 1966 in Athens, Greece) is a Professor at the Department of Informatics and Computer Technology of the Technological Educational Institute of Western Macedonia at Kastoria, Greece. She is a graduate of the Mathematics Department (1987) of the University of Athens, holds a Master's degree in Numerical Analysis and Computing (1989) from the Department of Mathematics of the University of Manchester and Ph.D. in Numerical Analysis (1992) from the University of Manchester, U.K. Her research interests are in numerical analysis and specifically in numerical solution of differential equations. She is the author of over 40 peer-reviewed publications and she is referee in scientific journals and conferences.



Theodore E. Simos (b. 1962 in Athens, Greece) is a Visiting Professor within the Distinguished Scientists Fellowship Program at the Department of Mathematics, College of Sciences, King Saud University, P. O. Box 2455, Riyadh 11451, Saudi Arabia and Professor at the Laboratory of Computational Sciences of the Department of Computer Science and Technology, Faculty of Sciences and Technology, University of Peloponnese, GR-221 00 Tripolis, Greece. He holds a Ph.D. on Numerical Analysis (1990) from the Department of Mathematics of the National Technical University of Athens, Greece. He is Highly Cited Researcher in Mathematics, Active Member of the European Academy of Sciences and Arts, Active Member of the European Academy of Sciences and Corresponding Member of European Academy of Sciences, Arts and Letters. He is Editor-in-Chief of three scientific journals and editor of more than 25 scientific journals. He is reviewer in several other scientific journals and conferences. His research interests are in numerical analysis and specifically in numerical solution of differential equations, scientific computing and optimization. He is the author of over 400 peer-reviewed publications and he has more than 2000 citations (excluding self-citations).



